

GEODESICALLY TRACKING QUASI-GEODESIC PATHS FOR COXETER GROUPS

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ABSTRACT. If Λ is the Cayley graph of a Gromov hyperbolic group, then it is a fundamental fact that quasi-geodesics in Λ are tracked by geodesics. Let (W, S) be a finitely generated Coxeter system and $\Lambda(W, S)$ the Cayley graph of (W, S) . For general Coxeter groups, not all quasi-geodesic rays in Λ are tracked by geodesics. In this paper we classify the Λ -quasi-geodesic rays that are tracked by geodesics. As corollaries we show that if W acts geometrically on a $\text{CAT}(0)$ space X , then $\text{CAT}(0)$ geodesics in X are tracked by Cayley graph geodesics (where the Cayley graph is equivariantly placed in X) and for any $A \subset S$, the special subgroup $\langle A \rangle$ is quasi-convex in X . We also show that if g is an element of infinite order for (W, S) then the subgroup $\langle g \rangle$ is tracked by a Cayley geodesic in $\Lambda(W, S)$ (in analogy with the corresponding result for word hyperbolic groups).

1. INTRODUCTION

Suppose G is a group with finite generating set A , and $\Lambda(G, A)$ is the Cayley graph of G with respect to A . If G is word hyperbolic then any quasi-geodesic in Λ is tracked by a geodesic (see [Sh]). The corresponding result for $\text{CAT}(0)$ groups is not true. Our main goal in this paper is to classify the quasi-geodesics in the Cayley graph of a finitely generated Coxeter system that are tracked by geodesics. We define a “bracket number” for a Cayley path in terms of the wall crossings of the path and our main theorem is that a quasi-geodesic ray or line is tracked by a geodesic iff the bracket number of the ray (line) is bounded. Our principal corollary to this theorem states that if (W, S) is a finitely generated Coxeter system, and W acts geometrically on a $\text{CAT}(0)$ space X , then the $\text{CAT}(0)$ geodesics of X are tracked by (W, S) -Cayley geodesics in X . If X is the Davis complex for (W, S) or even if W acts as a reflection group on X , the proof of the corollary is straightforward. Unfortunately, the reflection group argument has no analogue when W does not act as a reflection group on X . The principal corollary directly implies that if $A \subset S$ then the special subgroup $\langle A \rangle$ is quasi-convex in X .

If a group G acts geometrically on a $\text{CAT}(0)$ space X and one is interested in the asymptotic properties of X it is a considerable advantage to know that $\text{CAT}(0)$ geodesics in X are tracked by Cayley geodesics. Clearly,

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the algebraic properties of G are far more apparent in Cayley geodesics than in $\text{CAT}(0)$ geodesics. This theme is highlighted in [MRT] where local connectivity of boundaries of right angled Coxeter groups are analyzed.

The work of B. Bowditch and G. Swarup (see [S]) imply that 1-ended word hyperbolic groups have locally connected boundary. One can easily see from our tracking results that any 1-ended hyperbolic Coxeter group has locally connected boundary.

2. COXETER PRELIMINARIES

We use M. Davis' book [D] as a general Coxeter group reference for this section. A Coxeter system is a pair (W, S) where S is a generating set for the group W and W has presentation

$$\langle S : (s_i s_j)^{m(i,j)} \text{ for all } s_i, s_j \in S \rangle$$

where $m(i, j) \in \{1, 2, \dots, \infty\}$, $m(i, j) = 1$ iff $i = j$ (so all generators are order 2) and $m(i, j) = m(j, i)$. If $m(i, j) = \infty$, the element $s_i s_j$ is of infinite order (and the relation $(s_i s_j)^\infty$ is left out of the presentation).

A *reflection* in W is a conjugate of an element of S . If $w \in W$ and $s \in S$ then the edge labeled s in the Cayley graph $\Lambda(W, S)$ at the vertex w is mapped to itself by the reflection $ws w^{-1}$, so that the vertices w and ws are interchanged. I.e. the edge is reflected across its midpoint. The set of edges in Λ each fixed (set-wise) by a reflection is a *wall* of Λ . The walls of Λ partition the edges of Λ into disjoint sets. Notationally, we write a wall Q as $[e]$ where e is any edge of the wall Q and we define \bar{Q} to be the union of the edges of Q in Λ . An edge e (with say label $t \in S$) belongs to a wall Q corresponding to the reflection $ws w^{-1}$ iff a vertex of e is wq where $qtq^{-1} = s$. The closure of the compliment of a wall in Λ has exactly two components (which are interchanged by the reflection) called the *sides* of the wall. Two walls are *parallel* if all edges of one are on the same side of the other. If two walls are not parallel, then they *cross*. The following theorem due to B. Brink and R. Howlett (see theorem 2.8 of [BrH]) is a fundamental result concerning the wall structure of Λ .

Theorem 2.1. (Parallel Wall theorem) *Suppose (W, S) is a finitely generated Coxeter system and $\Lambda(W, S)$ the Cayley graph of W with respect to S . For each positive integer n there is a constant $P(n)$ such that the following holds: given a wall Q and a point p in Λ such that the distance from p to \bar{Q} is at least $P(n)$, then there exist n distinct pairwise parallel walls which separate \bar{Q} from p .*

For a path β in Λ and vertex t of β let the *bracket number* of t in β be the number of walls Q such that there is an edge of Q on either side of t in β . Denote the bracket number of t in β as $B(t, \beta)$. If τ is a subpath of β the *bracket number* of τ in β is the maximum of the numbers $B(t, \beta)$ for all vertices t of τ . Denote this number $B(\tau, \beta)$. Call $B(\beta) \equiv B(\beta, \beta)$ the *bracket number* of β .

3. WALL COMPUTATIONS

If α is an edge path in the Cayley graph Λ with consecutive vertices $a = v_0, v_1, \dots, v_n = b$, then an L -approximation to α is an edge path in Λ connecting a and b of the form $(\alpha_1, \dots, \alpha_n)$ where for all i , α_i is geodesic connecting w_{i-1} to w_i and w_i is within L of v_i . The points w_i are called *approximation points*.

Lemma 3.1. *Suppose (W, S) is a finitely generated Coxeter system, α is an edge path in the Cayley graph $\Lambda(W, S)$ connecting a and b , and β is an L -approximation of α . Then the bracket number $B(\beta)$ is bounded by a constant only depending on $B(\alpha)$, L and constants independent of the choice of α .*

Proof. Let the consecutive vertices of α be $a = v_0, v_1, \dots, v_n = b$, the approximation vertices of β be $a = w_0, w_1, \dots, w_m = b$ (so that $d_\Lambda(w_i, v_i) \leq L$ for all i) and β_i be the geodesic subpath of β connecting w_{i-1} to w_i . Then $\beta = (\beta_1, \dots, \beta_m)$. If x is a vertex of β_i and $B(x, \beta)$ is “large”, then (as each edge belongs to exactly one wall) there is a wall Q that brackets x on β that is “far” from x and hence far from v_i . Hence it suffices to bound the distance between v_i and a wall Q that brackets x on β . The Parallel Wall theorem implies this distance is large iff there is a large set \mathcal{Q} of (mutually parallel) walls that separate \bar{Q} from v_i , so it suffices to bound the size of the set \mathcal{Q} of walls that separate \bar{Q} from x . Say $j < i < k$ such that e_j and e_k are edges of β_j and β_k respectively, and each of e_j, e_k belongs to the wall Q . (See figure 1)

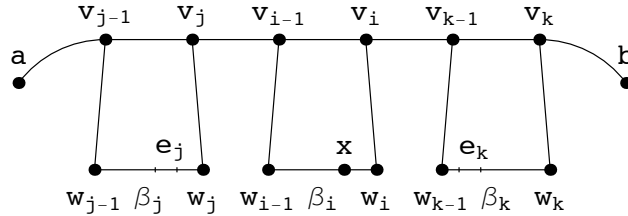


Figure 1

A path δ_j , that begins at the end point of e_j follows β_j to w_j and then travels geodesically from w_j to v_j has length $\leq 3L$. If $\alpha_{j,i}$ is the subpath of α from v_j to v_i , then the path $(\delta_j, \alpha_{j,i})$ must cross each wall of \mathcal{Q} . Similarly define a path from e_k to v_i (which also crosses each wall of \mathcal{Q}). Then at most $6L$ walls of \mathcal{Q} do not bracket v_i on α . This bounds the size of \mathcal{Q} by $6L + B(\alpha)$. \square

Lemma 3.2. *Suppose (W, S) is a Coxeter system and $\alpha = (e_1, \dots, e_n)$ is a geodesic edge path connecting vertices a and b in $\Lambda(W, S)$ such that α does not cross the wall Q . If e_0 is an edge at a and e_{n+1} an edge at b such that e_0 and e_{n+1} belong to the wall Q then each vertex of α is within $P(1)$ of \bar{Q} (where P is the function of theorem 2.1). In particular, if v is a vertex of α and v' the reflection of v across Q then $d(v, v') \leq 2P(1) + 1$.*

Proof. Otherwise, there is a wall Q' separating a vertex v of α from Q . Hence there is an edge of α between a and v that belongs to Q' and an edge of α between v and b that belongs to Q' . This is impossible as α is geodesic. \square

Proposition 3.3. *Suppose (W, S) is a Coxeter system and α is an edge path of $\Lambda(W, S)$ connecting a and b . Then there is an L -approximation β to α such that each vertex of β is on a geodesic connecting a and b and such that $L \leq (2P(1) + 1)B(\alpha)$.*

Proof. Let the consecutive vertices of α be $a = v_0, \dots, v_n = b$. For $0 < i < n$ we choose an approximation point w_i for v_i as follows. Let α_i be the geodesic from a to v_i and β_i the geodesic from v_i to b . Each wall of (α_i, β_i) is crossed exactly once or twice. The number of walls crossed twice by (α_i, β_i) is

$$N_i \equiv \frac{1}{2}(d(a, v_i) + d(v_i, b) - d(a, b)) \leq B(\alpha)$$

Let e be the last edge of α_i belonging to a wall which is crossed twice by (α_i, β_i) and d the edge of β_i in the same wall as e . (See figure 2.)

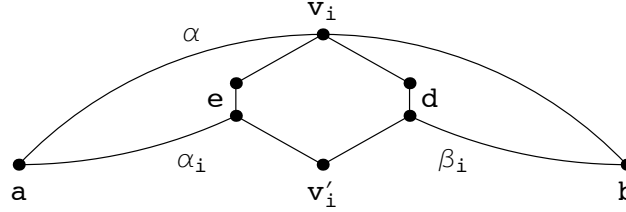


Figure 2

The segment of (α_i, β_i) between e and d is geodesic. Considering the reflection of this segment across the wall containing e and d (equivalently, delete e and d from (α_i, β_i)). Then we see that v'_i , the reflection of v_i , is within $2P(1)+1$ of v_i (lemma 3.2), and the distance from v'_i to a (respectively b) is less than that of v_i to a (respectively b). Hence $\frac{1}{2}(d(a, v'_i) + d(v'_i, b) - d(a, b)) < N_i$ and a geodesic from a to v'_i followed by a geodesic from v'_i to b crosses at most $N_i - 1$ walls twice. Continuing as above at most $N_i (\leq B(\alpha))$ such reflections are needed to move v_i to a point w_i on a geodesic between a and b , and so $d(w_i, v_i) \leq (2P(1) + 1)B(\alpha)$.

It remains to see that each vertex of a geodesic connecting w_i and w_{i+1} belongs to a geodesic connecting a and b . Consider the edge path $(\delta_i, \beta_i, \gamma_i)$ where δ_i is a geodesic connecting a to w_i , β_i is a geodesic connecting w_i to w_{i+1} and γ_i is a geodesic connecting w_{i+1} to b . The paths δ_i and γ_i only cross walls crossed by some (equivalently any) geodesic connecting a to b . If a vertex v of β_i is not on a geodesic connecting a and b then there is a wall R separating v from some (equivalently every) geodesic connecting a and b . As R separates v from a , and δ_i does not cross R , β_i must cross R between

w_i and v . Similarly β_i must cross R between v and w_{i+1} . This is impossible as β_i is geodesic. \square

If γ is an edge path in Λ connecting the vertices a and b , then each wall separating a and b is crossed an odd number of times by γ and each wall not separating a and b is crossed an even number of times by γ . If two edges of γ belong to the same wall then they may be “deleted” to obtain another path from a to b (i.e. if edges e and d of γ belong to the same wall Q , and τ is the segment of γ between e and d , then (e, τ, d) can be replaced in γ by τ' , where τ' is the reflection of τ across Q , to obtain a shorter path connecting a and b). If α is a geodesic connecting a and b then the walls separating a and b are the walls determined by the edges of α , so the walls separating a and b are in 1-1 correspondence with the edges of some (any) geodesic connecting a and b . The following observations are straightforward.

Lemma 3.4. *Suppose β is an edge path in Λ connecting the vertices a and b such that each vertex of β is on a geodesic connecting a and b . Then*

- i) each edge of β belongs to a wall that separates a from b ,*
- ii) each wall crossed by β is crossed an odd number of times, and*
- iii) if c and d are vertices of β then any wall separating c and d also separates a and b .*

The next result is a slightly more sophisticated version of lemma 3.2.

Lemma 3.5. *Suppose α is a geodesic edge path in Λ connecting the vertices a and b , v is a vertex of α , and a and b are each within distance A of \bar{Q} for some wall Q . Then v is within distance $2A(2P(1) + 1) + P(1)$ of \bar{Q} .*

Proof. Let a' (respectively b') be a vertex of \bar{Q} within A of a (respectively b) and on the same side of Q as is a (respectively b). Let β (respectively γ) be a geodesic from a' to a (respectively b to b').

Case 1. The geodesic α does not cross Q .

In this case the path $\delta_0 \equiv (\beta, \alpha, \gamma)$ does not cross Q . Since $|\beta| \leq A$ and $|\gamma| \leq A$, a sequence of at most $2A$ deletions (the first in the path δ_0) determines a geodesic connecting a' to b' which does not cross Q .

*) Each deletion is taken so that if e and d are the deleted edges, then the subpath determined by e (or d) along with the subpath between e and d is geodesic.

If e_1 and d_1 are the first such deletion edges (so e_1 and d_1 are edges of δ_0) then let δ_1 be obtained from δ_0 by deleting e_1 and d_1 . If v is not between e_1 and d_1 then v is a vertex of δ_0 . If v is between e_1 and d_1 , then v_1 , the reflection of v across the wall $[e_1] = [d_1]$, is within $2P(1) + 1$ of v , by lemma 3.2. (Note that the hypotheses of lemma 3.2 are satisfied since we require condition *.) In any case δ_1 contains a vertex v_1 within $2P(1) + 1$ of v . If e_2 and d_2 are deleting edges of δ_1 (satisfying *), then let δ_2 be obtained from δ_1 by deleting e_2 and d_2 . Lemma 3.2 implies δ_2 contains a vertex v_2 within

$2P(1) + 1$ of v_1 and so within $2(2P(1) + 1)$ of v . Inductively, after $K \leq 2A$ deletions, we obtain a geodesic δ_K connecting a' and b' , and δ_K contains a vertex v_K within $K(2P(1) + 1)$ of v . Note that δ_k does not cross Q . By lemma 3.2, v_K is within $P(1)$ of \bar{Q} so that v is within $2A(2P(1) + 1) + P(1)$ of \bar{Q} . This completes case 1.

Case 2. Suppose α crosses Q .

Say the edge e of α between v and b belongs to Q . Repeat the case 1 argument with δ_0 replaced by (β, α') , where α' is the subsegment of α from a to the initial point of e . Similarly if $e \in Q$ is an edge of α between a and v . Note that in both case 2 scenarios, at most A deletions are required to straighten to a geodesic, so the bound is reduced to $A(2(P(1)+1)+P(1))$. \square

4. TRACKING QUASI-GEODESICS

We are interested in quasi-geodesic edge paths in Λ . An *edge path* in Λ is a continuous map $\beta : [0, n] \rightarrow \Lambda$ such that $n \in \mathbb{Z}^+$ and for each non-negative integer k , β maps the interval $[k, k+1]$ isometrically to an edge of Λ . Similarly if $\beta : [0, \infty) \rightarrow \Lambda$, then β is called a *ray* and, if $\beta : (-\infty, \infty) \rightarrow \Lambda$ then β is called a *line*. An edge path β is a (λ, ϵ) -*quasi-geodesic* if for each pair of integers s and t , $|s - t| \leq \lambda d(\beta(s), \beta(t)) + \epsilon$. If α and β are edge paths, then β is K -*tracked* by α if each vertex of β is within K of a vertex of α .

Lemma 4.1. *For $i \in \{1, 2\}$ suppose β_i is a (λ_i, ϵ_i) -quasi-geodesic edge path in Λ , β_1 is K -tracked by β_2 and $\beta_1(0)$ is within K of $\beta_2(0)$. Assume both β_1 and β_2 are bi-infinite, or both are rays, or both are finite length and the terminal points of β_1 and β_2 are within K of one another. Then β_2 is $(\lambda_2(2K + 1) + \epsilon_2 + K)$ -tracked by β_1 .*

Proof. Since each vertex of β_1 is within K of a vertex of β_2 , we may define an integer function a such that for each integer i (in the domain of β_1), $\beta_1(i)$ is within K of $\beta_2(a(i))$. We take $a(0) = 0$ and if β_i has n_i edges then $a(n_1) = n_2$.

The first two inequalities follow from the definitions and the third follows from the first two.

$$\begin{aligned}
 1) \quad & \frac{|a(m+i) - a(m)| - \epsilon_2}{\lambda_2} - 2K \leq d(\beta_2(a(m+i)), \beta_2(a(m))) - 2K \leq \\
 & d(\beta_1(m+i), \beta_1(m)) \leq d(\beta_2(a(m+i)), \beta_2(a(m))) + 2K \leq |a(m+i) - a(m)| + 2K \\
 2) \quad & \frac{i - \epsilon_1}{\lambda_1} \leq d(\beta_1(m+i), \beta_1(m)) \leq i \\
 3) \quad & \frac{i - \epsilon_1}{\lambda_1} - 2K \leq |a(m+i) - a(m)| \leq
 \end{aligned}$$

$$\lambda_2(d(\beta_1(m+i), \beta_1(m)) + 2K) + \epsilon_2 \leq (i + 2K)\lambda_2 + \epsilon_2$$

The inequality $|a(i+1) - a(i)| \leq \lambda_2(2K+1) + \epsilon_2$ implies if k is between $a(i)$ and $a(i+1)$ for some i then $\beta_2(k)$ is within $\lambda_2(2K+1) + \epsilon_2 + K$ of $\beta_1(i)$. In the case β_1 and β_2 are finite, the condition that terminal points are within K of one another (so that $a(n_1) = n_2$) implies that every integer in the domain of β_2 is between $a(i)$ and $a(i+1)$ for some i and this case is finished. If β_1 and β_2 are rays then $a(i)$ is non-negative and equation 3) (with $m = 0$) implies $a(i)$ is arbitrarily large for large i and again every integer in the domain of β_2 is between $a(i)$ and $a(i+1)$ for some i . If β_1 and β_2 are bi-infinite, then the $a(i)$ may be positive or negative and (again by 3)) for large $|i|$, $|a_i|$ is large, and $\lim_{i \rightarrow +\infty} a(i) = \pm\infty$ and $\lim_{i \rightarrow -\infty} a(i) = \pm\infty$. It remains to see $\lim_{i \rightarrow +\infty} a(i) \neq \lim_{i \rightarrow -\infty} a(i)$. Equality is impossible, since otherwise, for every large positive integer i , $a(-i)$ would be between $a(j)$ and $a(j+1)$ for some (depending on i) large positive integer j . But equation 3) implies $a(j)$ and $a(j+1)$ are relatively close and $a(-i)$ and $a(j)$ are far apart. \square

Proposition 4.2. *Suppose β is a quasi-geodesic edge path ray in Λ and β is tracked by a geodesic, then β has bounded bracket number.*

Proof. Assume that β is a (λ, ϵ) -quasi-geodesic. Suppose α is a geodesic such that each vertex of β is within L of a vertex of α . For each integer $n \geq 0$, choose an integer $a(n)$ such that $d(\beta(n), \alpha(a(n))) \leq L$. We assume that $a(0) = 0$.

The next two equations follow from the definitions and the third follows from the first two.

$$a(n) - 2L \leq d(\beta(n), \beta(0)) \leq a(n) + 2L$$

$$\frac{n - \epsilon}{\lambda} \leq d(\beta(n), \beta(0)) \leq n$$

$$\frac{n - \epsilon}{\lambda} - 2L \leq a(n) \leq n + 2L$$

Claim 4.3. *Suppose K is an integer larger than $\lambda(4L+1) + \epsilon$. Then for any integer n , $a(n+K) > a(n)$.*

Proof. Note that if $m \geq \lambda(n+4L) + \epsilon$ then $a(m) > n + 2L > a(n)$. So if $K > \lambda(4L+1) + \epsilon$, and $a(n+K) \leq a(n)$, then there is a last integer $K_1 > \lambda(4L+1) + \epsilon$ such that $a(n+K_1) \leq a(n)$. Then (see figure 3)

$$a(n+K_1+1) > a(n) \geq a(n+K_1)$$

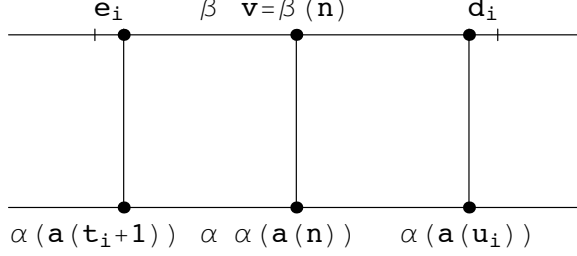


Figure 3

Since $d(\beta(n + K_1), \beta(n + K_1 + 1)) = 1$ for all n , and $d(\beta(i), \alpha(a(i))) \leq L$ for all i , we have

$$d(\alpha(a(n + K_1)), \alpha(a(n + K_1 + 1))) \leq 2L + 1$$

But as $\alpha(a(n))$ is between $\alpha(a(n + K_1))$ and $\alpha(a(n + K_1 + 1))$ on the geodesic α ,

$$d(\alpha(a(n)), \alpha(a(n + K_1 + 1))) \leq 2L + 1$$

Then $d(\beta(n), \beta(n + K_1 + 1)) \leq 4L + 1$. But

$$d(\beta(n), \beta(n + K_1 + 1)) \geq \frac{1}{\lambda}(K_1 + 1 - \epsilon) > 4L + 1$$

the desired contradiction (so the claim is proved). \square

Now suppose $v \equiv \beta(n)$ is a vertex of β with bracket number at least $2\lambda(4L + 1) + 2\epsilon + K$. Then (by the pigeon hole principal) there are K distinct walls, Q_1, \dots, Q_K such that for each $i \in \{1, \dots, K\}$, there is an edge e_i of β preceding v and an edge d_i of β following v such that e_i and d_i belong to the wall Q_i , the subpath of β between e_i and d_i does not cross Q_i , e_i is not one of the $\lambda(4L + 1) + \epsilon$ edges of β immediately preceding v and d_i is not one of the $\lambda(4L + 1) + \epsilon$ edges of β immediately following v . I.e. $e_i = \beta([t_i, t_i + 1])$ where $t_i + 1 \leq n - \lambda(4L + 1) - \epsilon$ and $d_i = \beta([u_i, u_i + 1])$ where $u_i \geq n + \lambda(4L + 1) + \epsilon$. (See figure 4.)

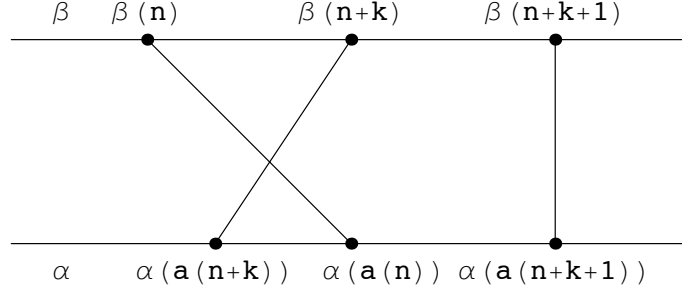


Figure 4

By claim 4.3, $a(t_i + 1) < a(n) < a(u_i)$. Hence, by lemma 3.5, $\alpha(a(n))$ is within $2L(2P(1) + 1) + P(1)$ of the wall Q_i . For x a vertex of Λ , let $C(k)$ be the number of distinct walls that pass within k of x . Note that C is independent of vertex in Λ . Hence $K \leq C(2L(2P(1) + 1) + P(1))$, bounding the bracket number of a vertex of β . \square

5. PROOF OF MAIN THEOREM

In order to prove the main theorem, we need two results, one due to B. Brink and R. Howlett [BrH], and a second, due to R. P. Dilworth [Di].

Theorem 5.1. (*Brink-Howlett*) Suppose (W, S) is a finitely generated Coxeter system, and $\Lambda(W, S)$ is the Cayley graph of W with respect to S . There is a bound $F_{(W, S)}$ on the number of mutually crossing walls of Λ .

Dilworth's theorem requires several definitions. If A is a partially ordered set (a set with reflexive, antisymmetric and transitive binary relation \leq on A), then any two elements x and y are *comparable* if either $x \leq y$ or $y \leq x$. Otherwise they are in *incomparable*. A subset C of A is a *chain* when every pair of points in C is a comparable pair. A subset B of A is called an *antichain* when every pair of points in B is an incomparable pair. The number of points in a maximal antichain is called the *width* of A .

Theorem 5.2. (*Dilworth*) If A is a partially ordered set of width w , then A can be partitioned into w chains.

Suppose x and y are vertices of $\Lambda(W, S)$ and $\mathcal{W}_{(x, y)}$ is the set of walls that separate x and y . We partially order $\mathcal{W}_{(x, y)}$ by saying $P \leq Q$ if either $P = Q$, or P and Q are parallel and P separates x from Q . Note that P and Q are parallel walls of $\mathcal{W}_{(x, y)}$, iff they are comparable. Hence P and Q are incomparable iff they cross. By proposition 5.1, the width of $\mathcal{W}_{(x, y)}$ is $F_{(W, S)}$. Applying Dilworth's theorem we have:

Proposition 5.3. *Suppose (W, S) is a finitely generated Coxeter system, and $\Lambda(W, S)$ is the Cayley graph of W with respect to S . For any vertices x and y of Λ the walls separating x and y can be partitioned into at most $F_{(W, S)}$ chains (where any two walls in the same chain are parallel).*

Say a path is *geodesic with respect to a set of walls* if the path crosses each wall of the set either 0 or 1 times. The following lemma is clear.

Lemma 5.4. *Suppose α is an edge path in Λ and α is geodesic with respect to the set of parallel walls \mathcal{Q} . If a subpath of α is replaced by a geodesic edge path, then the resulting edge path is geodesic with respect to \mathcal{Q} .*

Theorem 5.5. *Suppose (W, S) is a finitely generated Coxeter system, α is a (λ, ϵ) -quasi-geodesic edge path from a to b in the Cayley graph $\Lambda(W, S)$. Then there is an integer K , depending only on Λ , λ , ϵ and the bracket number B of α , and a Λ -geodesic β connecting a and b such that α is K -tracked by β .*

Proof. The proof is a double induction argument. By proposition 5.3, the walls separating a and b can be partitioned into at most F sets $\mathcal{Q}_1, \dots, \mathcal{Q}_A$, where two walls in the same set are parallel. The “outside” induction is on the number $A(\leq F)$ of sets of walls separating a and b . The fact that A is bounded by F is critical to the argument that follows. Note that if $A = 1$ then all walls separating a and b are parallel. In this case, the walls separating a and b are ordered as Q_1, \dots, Q_m where for $i < j < k$, Q_j separates Q_i from Q_k . Hence, there is a unique, geodesic edge path β connecting a and b , and β crosses Q_1 , then Q_2, \dots . By proposition 3.3, the path α is approximated by a path α' , such that each vertex of α' is on a geodesic connecting a and b . The path α' only crosses the walls separating a and b (see lemma 3.4) and, in this case, is geodesic, modulo backtracking. Eliminating backtracking on α' produces β . Each vertex of α' is a vertex of β and the basis case is complete.

Assume the statement of the theorem is true if A , the number of sets of walls separating a and b , is less than or equal to $M - 1$. Suppose there are M sets of walls $(\mathcal{Q}_1, \dots, \mathcal{Q}_M)$ separating a and b . By proposition 3.3 we may assume every vertex of α is on a geodesic connecting a and b , so that α only crosses walls separating a and b and α crosses each such wall an odd number of times. The second induction is on $N(\leq M)$, the number of sets of walls, \mathcal{Q}_i , such that α is not geodesic with respect to \mathcal{Q}_i . If $N = 0$, then α is geodesic. Assume the statement of the theorem is true for $N = K - 1$ (when the number of sets of walls separating a and b is $\leq M$). Assume the \mathcal{Q}_i are arranged so that α is geodesic with respect to \mathcal{Q}_i for $K + 1 \leq i \leq M$. Write α as (e_1, \dots, e_n) with consecutive vertices $a \equiv a_1, \dots, a_n \equiv b$. Let i be the first integer such that e_i is an edge of a wall of \mathcal{Q}_K and for some $j > i$, e_j and e_i are in the same wall Q . Now assume j is the largest integer such that $e_j \in Q$. Since α crosses Q an odd number of times, the path $\alpha_{i,j} \equiv (e_i, \dots, e_{j-1})$ (from a_i to a_j) crosses Q an even number of times. A geodesic $\beta_{i,j}$ connecting a_i to a_j does not cross Q . Since all walls of \mathcal{Q}_K are

parallel to one another, $\beta_{i,j}$ does not cross a wall of \mathcal{Q}_K . Hence a_i and a_j are not separated by a wall of \mathcal{Q}_K . By proposition 3.3, $\alpha_{i,j}$ is close to $\alpha'_{i,j}$ a quasi-geodesic edge path connecting a_i to a_j , such that each vertex of $\alpha'_{i,j}$ is on a geodesic connecting a_i to a_j . By lemma 3.4, each wall separating a_i and a_j also separates a and b , and the number of sets of walls separating a_i and a_j is less than M . By (outside) induction, there is a geodesic $\beta_{i,j}$ connecting a_i and a_j which tracks $\alpha'_{i,j}$ and therefore tracks $\alpha_{i,j}$. Replace $\alpha_{i,j}$ by $\beta_{i,j}$. The resulting path, α_1 crosses Q exactly once at e_j . The walls of \mathcal{Q}_K are ordered as Q_1, Q_2, \dots so that if $i < j$, then Q_i separates a from Q_j , and Q_j separates Q_i from b . A wall of \mathcal{Q}_K preceding Q in this ordering is not crossed by α_1 after e_j . Hence if $\mathcal{Q} \subset \mathcal{Q}_K$ is the set of walls of \mathcal{Q}_K preceding Q and including Q , then α_1 is geodesic with respect to \mathcal{Q} and (by lemma 5.4), α_1 is geodesic with respect to each set \mathcal{Q}_i for $i > K$. Suppose e_k is the first edge of α_1 such that e_k is an edge of a wall Q of \mathcal{Q}_K , and for some $l > k$, $e_l \in Q$. Then e_k follows e_j on α_1 , and if we assume e_l is the last edge of α_1 in Q , then as above (e_k, \dots, e_{l-1}) can be replaced by a geodesic close to (e_k, \dots, e_{l-1}) . Continuing, the resulting path is geodesic with respect to \mathcal{Q}_K and by induction, the theorem follows. Note that the bound F for Λ (on the number of sets of parallel walls are necessary to partition the set of walls separating two points a and b of Λ), limits the total number of times the induction steps are carried out to arrive at a geodesic. \square

6. CONSEQUENCES OF THE MAIN THEOREM

Corollary 6.1. *Suppose (W, S) is a finitely generated Coxeter system, and $\Lambda(W, S)$ is the Cayley graph of W with respect to S . Any infinite or bi-infinite (λ, ϵ) -quasi-geodesic edge path α with bounded bracket number B is K' -tracked by an edge path geodesic where K' is a constant only depending on λ , ϵ , B and S .*

Proof. The proof is a standard local finiteness argument in both the infinite and bi-infinite case. We give the bi-infinite case. Write α as the edge path $(\dots, e_{-1}, e_0, e_1, \dots)$ in Λ . Let v_i be the initial point of e_i . By theorem 5.5, there is a Λ -geodesic β_n which K -tracks $\alpha_n \equiv (e_{-n}, \dots, e_n)$. Note that every vertex of β_n is within $2K$ of a vertex of α . For each positive integer n , some vertex x_n of α_n is within K of v_0 . Hence there is an infinite number of x_n that are equal. Of this infinite subcollection of x_n , infinitely many have the same pair of edges one preceding and one following x_n on β_n , of this infinite collection of x_n there is an infinite subcollection that have the same four edges - the two preceding and the two following x_n being exactly the same. Continuing, we have a bi-infinite geodesic β and each vertex of β is within $2K$ of a vertex of α . As α is a (λ, ϵ) -quasi-geodesic, lemma 4.1 implies each point of α is within $\lambda(4K + 1) + \epsilon + 2K$ of β . \square

The next result follows directly from proposition 4.2 and corollary 6.1.

Corollary 6.2. *Suppose (W, S) is a finitely generated Coxeter system, and $\Lambda(W, S)$ is the Cayley graph of W with respect to S . Then a quasi-geodesic edge path ray in Λ is tracked by a geodesic iff it has bounded bracket number.*

A metric space (X, d) is called a *geodesic metric space* if every pair of points are joined by a geodesic. It is *proper* if for any $x \in X$, the ball of radius r about x is compact for all positive numbers r . A group W acts *geometrically* on a space if the action is properly discontinuous, co-compact and by isometries.

Let (X, d) be a proper complete geodesic metric space. If $\triangle abc$ is a geodesic triangle in X , then we consider $\triangle \bar{a}\bar{b}\bar{c}$ in \mathbb{E}^2 , a triangle with the same side lengths, and call this a *comparison triangle*. Then we say X satisfies the *CAT(0) inequality* if given $\triangle abc$ in X , then for any comparison triangle and any two points p, q on $\triangle abc$, the corresponding points \bar{p}, \bar{q} on the comparison triangle satisfy

$$d(p, q) \leq d(\bar{p}, \bar{q})$$

If (X, d) is a CAT(0) space, then the following basic properties hold:

- (1) The distance function $d: X \times X \rightarrow \mathbb{R}$ is convex.
- (2) X has unique geodesic segments between points.
- (3) X is contractible.

For details, see [BH].

Suppose (W, S) is a finitely generated Coxeter system, $\Lambda(W, S)$ is the Cayley graph of W with respect to S and W acts geometrically on a CAT(0) space X . Define $\Lambda_x \subset X$ to have as vertices, the orbit Wx , and CAT(0) geodesic edge connecting w_1x and w_2x (for $w_i \in W$) when there is $s \in S$ such that $w_1s = w_2$. There is a proper W -equivariant map $P_x: \Lambda \rightarrow \Lambda_x$ so that P_x maps the identity vertex of Λ to x .

Intuitively, the next result says that when a Coxeter group acts geometrically on a CAT(0) space, CAT(0) geodesics are tracked by Cayley graph geodesics. This result generalizes the right angled version of the same result in [MRT].

Corollary 6.3. *Suppose (W, S) is a finitely generated Coxeter system, and $\Lambda(W, S)$ is the Cayley graph of W with respect to S and W acts geometrically on the proper CAT(0) space X . If x is a point of X not fixed by any element of W , and Λ_x is the copy of Λ at x , then any CAT(0) geodesic ray in X is tracked by a Cayley graph geodesic in Λ_x .*

Proof. For a given CAT(0) geodesic α we find a Cayley graph geodesic β such that $P_x(\beta)$ tracks α . It suffices to find λ, ϵ, K and B such that any (finite) CAT(0) geodesic α is K -tracked by a Cayley (λ, ϵ) -quasi-geodesic with bracket number $\leq B$. Since W acts co-compactly on X , there is an integer K_1 such that every point of X is within K_1 of the orbit Wx . For each integer $0, 1, \dots, N$ such that N is less than or equal to the length of α , choose a point $v_i x$ of Wx within K_1 of $\alpha(i)$. Let β_i be a Λ -geodesic

connecting v_i to v_{i+1} and β be the Λ -edge path $(\beta_0, \beta_1, \dots)$. Since the map $P_x : \Lambda \rightarrow \Lambda_x$ is quasi-isometric, there are numbers λ and ϵ such that any such β is a (λ, ϵ) -quasi-geodesic in Λ and numbers D_Λ and D_X such that the length of any β_i is less than or equal to D_Λ (in Λ) and every point of such a $P_x(\beta_i)$ is within D_X of $\alpha(i)$ (in X). Certainly every point of α is within $K \equiv K_1 + 1$ of $P_x(\beta)$.

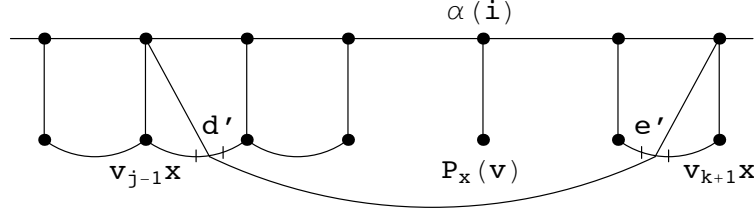


Figure 5

Hence it suffices to bound the bracket number of such a β . If v is a vertex of β_i and e and d are edges of β preceding and following v respectively such that e and d belong to the same wall Q of Λ , then e is an edge of β_j and d is an edge of β_k where $j \leq i \leq k$. The mid-points e' of $P_x(e)$ and d' of $P_x(d)$ are fixed (in Λ_x and X) by the reflection $r_Q \in W$ for the wall Q (as are the mid-points of e and d in Λ). Hence the geodesic in X connecting d' and e' is fixed by r_Q . Now, d' (respectively e') is within D_X of $\alpha(j-1)$ (respectively $\alpha(k+1)$) and $P_x(v)$ is within D_X of $\alpha(i)$. By the CAT(0) inequality for quadrilaterals (in particular for the quadrilateral determined by d' , e' , $\alpha(j-1)$, and $\alpha(k+1)$) $\alpha(i)$ is within D_X of a point of the X -geodesic connecting d' to e' and hence $\alpha(i)$ is within D_X of a fixed point of r_Q . (See figure 5.)

Since the action of W on X is properly discontinuous, there is a bound B on the number of reflections r_Q such that r_Q does not take the ball of radius D_X centered at $v(i) \in X$ (equivalently centered at any $x \in X$) off of itself. Hence there cannot be more than B walls bracketing the vertex v of β . \square

Remark 6.4. Note that the above proof is valid even when W does not act co-compactly on the CAT(0) space X , as long as the CAT(0) geodesic remains a bounded distance from Λ_x for some x .

The following result answers a question posed by K. Ruane.

Corollary 6.5. Suppose (W, S) is a finitely generated Coxeter group acting geometrically on the CAT(0) space X . For $x \in X$ let Λ_x be the copy of the Cayley graph of (W, S) in X , (with W -equivariant map $P_x : \Lambda(W, S) \rightarrow \Lambda_x$). Then for each subset $A \subset S$, the subgroup $\langle A \rangle$ is quasi-convex in X . (I.e. $P_x(\langle A \rangle)$ is quasi-convex in X .)

Proof. Let K be the tracking constant from corollary 6.3. Suppose $a_1, a_2 \in A$ and α is a CAT(0) geodesic in X from $P_x(a_1)$ to $P_x(a_2)$. Let β be a Λ_x ,

edge path geodesic which K -tracks α . I.e. there is a $\Lambda(W, S)$ geodesic β' , from a_1 to a_2 such that $P_x(\beta') = \beta$. Since $a_i \in A$, the edge labels of β' are all in A . This means all vertices of β' are in $\langle A \rangle$, and so the image of α is within K of $P_x(\langle A \rangle)$. \square

The next result says that elements of infinite order in a Coxeter group are tracked by geodesics in the standard Cayley graph.

Corollary 6.6. *Suppose (W, S) is a finitely generated Coxeter system and $g \in W$ is an element of infinite order. Then in the Cayley graph $\Lambda(W, S)$ the elements $\{\dots, g^{-2}, g^{-1}, 1, g, g^2, \dots\}$ are tracked by a Cayley graph geodesic.*

Proof. By G. Moussong [Mo], all finitely generated Coxeter groups are CAT(0). Let X be any CAT(0) space such that W acts geometrically on X . The min set of g contains a geodesic line l that is invariant under the action of g . Let x be any point in X and Λ_x the copy of $\Lambda(W, S)$ in X at x . Let α be an S -geodesic for g . Observe that the edge path line l_g in Λ_x determined by positive and negative iterates of α at x is a bounded distance from l . The proof of corollary 6.3 shows that l_g is a quasi-geodesic with bounded bracket number and so by corollary 6.1 is tracked by a Cayley graph geodesic. \square

One of the fundamental asymptotic results for word hyperbolic groups is that 1-ended word hyperbolic groups have locally connected boundary. This result follows from a long program of results by several authors, notably B. Bowditch, and concluded by G. Swarup [S]. To give a feeling for the reach of our results, we outline an elementary proof of this fact for Coxeter groups.

Corollary 6.7. *If W is a 1-ended word hyperbolic Coxeter group then the boundary of W is locally connected.*

Proof. We use an elementary form of a construction of a “filter” in [MRT] (where a partial classification of right angled Coxeter groups with locally connected boundaries is produced). Suppose W acts geometrically on the CAT(0) space X , with base point x . Let Λ_x be the copy of the Cayley graph of (W, S) at x in X with proper W -equivariant map $P_x : \Lambda(W, S) \rightarrow \Lambda_x$. Suppose r and s are “close” geodesic rays in X , with $r(0) = s(0) = x$. Choose Λ (edge path) geodesics r' and s' at $*$ (the identity vertex of $\Lambda(W, S)$), such that $P_x(r')$ and $P_x(s')$ K -track r and s respectively. Since r and s are close in ∂X , we may assume that r' and s' have long initial segments with “close” terminal points. For simplicity we assume these initial segments agree. If y is the last vertex of this common initial segment, say the edge of r' following y has label a_1 and the edge of s' following y has label b_1 . The presentation diagram $\Gamma(W, S)$ of (W, S) has vertex set S and an edge labeled $m(i, j)$ between distinct vertices s_i, s_j if $m(i, j) \neq \infty$. Since W is 1-ended no subset A of S with $\langle A \rangle$ a finite group separates Γ (see corollary 16 of [MT]). The set B of S -elements that label edges at y with end points closer to $*$ than y is to $*$ generates a finite subgroup of W . The set of vertices of Γ corresponding to B does not separate Γ and B does not

contain a_1 or b_1 . Hence there is an edge path in Γ from a_1 to b_1 avoiding B . Let the consecutive vertices of this path be $a_1 = v_1, v_2, \dots, v_n = b_1$. If $q(i, i+1)$ is the (finite) order of $v_i v_{i+1}$ then the relation $(v_i, v_{i+1})^{q(i, i+1)}$ determines a loop at $y \in \Lambda$ such that the two half loops at y making up this loop extend the Cayley geodesic from $*$ to y . Consider the subgraph F_1 of Λ determined by the edge paths r', s' and the edge loops for each $v_i v_{i+1}$. Each v_i determines an edge of F_1 (with label v_i) beginning at y . At the end point of this edge there are two edges of F_1 that extend a Cayley geodesic from $*$ to y . Build a set of loops as with a_1 and b_1 for each of these pairs of edges. Then F_2 is F_1 union all new loops. Continuing we build a 1-ended subgraph $F = \cup_{i=1}^{\infty} F_i$ of Λ such that for each vertex v of F , not on the common overlap of r' and s' , there is a Cayley geodesic from $*$ to v in F which passes through y . We claim that L , the limit set of $P_x(F)$ is a “small” connected set containing r and s (and so ∂X is locally connected). Certainly, r and s are in L . Since F is 1-ended and P_x is proper, L is connected. If v is a vertex of F , then there is a Cayley geodesic α_v from $*$ to v (which passes through y for all but finitely many v). If $z \in L$ then let z_1, z_2, \dots be a sequence of vertices of F such that $P_x(z_i)$ converges to z . The CAT(0) geodesic from x to $P_x(z_i)$ is K -tracked by a Cayley geodesic β_i in Λ_x . As W is word hyperbolic the Cayley geodesics $P_x(\alpha_{v_i})$ and β_i (with the same end points) must δ -fellow travel (for a fixed constant δ). In particular each β_i must pass “close” to $P_x(y)$ and so z is close to both r and s in $\partial X \equiv \partial W$. \square

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